

# Calibrated sensitivity models

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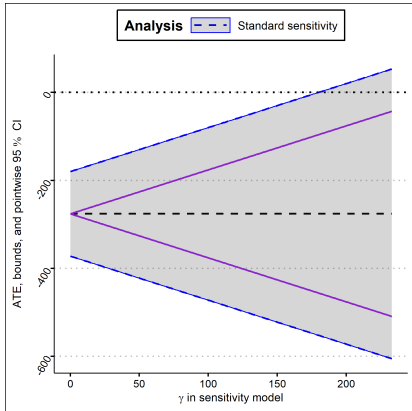
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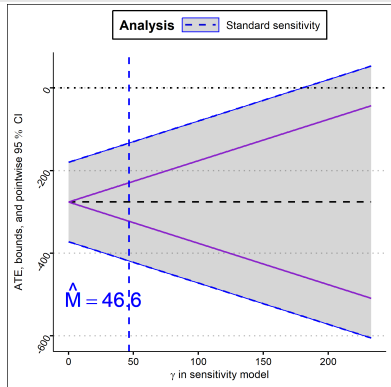
# Partial identification sensitivity model: $U \leq \gamma$

E.g.,  $U$  is odds ratio of propensity score [Rosenbaum, 2002, Tan, 2006]



**Issue #1: With nonparametric methods, difficult to interpret  $\gamma$  (e.g., how big is  $\gamma = 190$ ?)**

**Post hoc calibration: estimate measured confounding  $M$**



**Issue #2: Uncertainty in  $\hat{M}$  is unaccounted for**

## Solution: calibrated sensitivity models

Sensitivity model:  $U \leq \gamma$

e.g.,  $U$  is odds ratio of propensity score [Rosenbaum, 2002, Tan, 2006]

**Calibrated sensitivity models:**  $U \leq \Gamma M$

→ put measured confounding in the model!

Issue #1:  $\gamma$  difficult to interpret

$\Gamma$  is interpretable bound on **unit-less** ratio  $U/M$

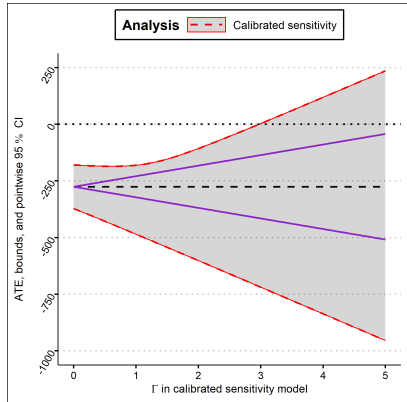
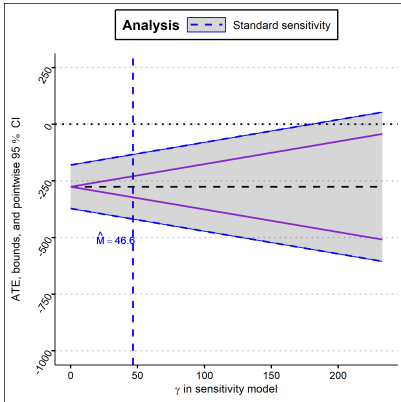
Issue #2: uncertainty in  $\hat{M}$  is unaccounted for

One can develop methods to account for uncertainty in estimating measured confounding

Issue #3: choice of measured confounding not justified

Clearer researchers must justify choice of measured confounding because explicit assumption in model

# Accounting for uncertainty in $\hat{M}$ can change results!



- red wider than blue  $\implies$  less robust to unmeasured confounding
- red narrower than blue  $\implies$  more robust to unmeasured confounding

Shape of red CI depends on covariance between estimators for bounds and measured confounding  $M$

# Setup

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# Setup: data and assumptions

Observe  $Z_i = \{X_i, A_i, Y_i\}$  for  $i = 1, \dots, n$  where  $Z_i \stackrel{iid}{\sim} \mathcal{P}$

$X \in \mathbb{R}^d$  are  **$d$ -dimensional covariates**

$A \in \{0, 1\}$  is a **binary treatment**

$Y \in \mathbb{R}$  is an **outcome**

$Y^a$  is the **potential outcome** under treatment  $a$

$W$  are **unmeasured confounders**

**Nuisance functions:**

$\pi(X) = \mathbb{P}(A = 1 \mid X)$  is the **propensity score**

$\mu_a(X) = \mathbb{E}(Y \mid A = a, X)$  is the **outcome regression function**

**Causal assumptions:**

1. **Consistency:**  $Y = Y^a$  if  $A = a$
2. **Positivity:**  $\exists \varepsilon > 0$  s.t.  $\mathbb{P}\{\varepsilon \leq \pi(X) \leq 1 - \varepsilon\} = 1$ .

**Average Treatment Effect (ATE):**  $\psi_* = \mathbb{E}(Y^1 - Y^0)$

# Calibrated sensitivity models

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# Model choices

Calibrated sensitivity models:  $U \leq \Gamma M$

where

- $U$  is unmeasured confounding,
- $\Gamma$  is the sensitivity parameter
- $M$  is measured confounding (analogous to  $U$ )

**Example:** [Rosenbaum, 2002]

$$\underbrace{\sup_{x, w, \tilde{w}} \left| \log \left[ \frac{\text{odds}\{\pi(x, w)\}}{\text{odds}\{\pi(x, \tilde{w})\}} \right] \right|}_{U} \leq \Gamma \left( \underbrace{\max_{j \in \{1, \dots, d\}} \sup_{x_{-j}, x_j, \tilde{x}_j} \left| \log \left[ \frac{\text{odds}\{\pi(x_{-j}, x_j)\}}{\text{odds}\{\pi(x_{-j}, \tilde{x}_j)\}} \right] \right|}_{M} \right)$$

$x_j$  is  $j^{\text{th}}$  covariate and  $x_{-j}$  is  $d - 1$  covariates with  $j^{\text{th}}$  removed



# Model choices: measured confounding

## Measured confounding $M$ :

- Which subsets measured confounding includes,
- Whether measured confounding is a max or an avg

$$\text{Maximum leave-one-out} = \max_{j \in \{1, \dots, d\}} \sup_{x_{-j}, x_j, \tilde{x}_j} \left| \log \left[ \frac{\text{odds}\{\pi(x_{-j}, x_j)\}}{\text{odds}\{\pi(x_{-j}, \tilde{x}_j)\}} \right] \right|$$

$$\text{Average leave-some-out} = \frac{1}{|S|} \sum_{S \in \mathcal{S}} \sup_{x_{-S}, x_S, \tilde{x}_S} \left| \log \left[ \frac{\text{odds}\{\pi(x_{-S}, x_S)\}}{\text{odds}\{\pi(x_{-S}, \tilde{x}_S)\}} \right] \right|$$

→ exclude **multiple covariates** because suspect **correlated** and **joint effect** better proxy for unmeasured confounder

$S$  is an index on  $\{1, \dots, d\}$ ,  $x_S$  are covariates corresponding to  $S$  (e.g.,  $x_{\{1,2\}}$  are first two covs), and  $x_{-S}$  are  $d - |S|$  covs with  $x_S$  removed.

# Partial Identification

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## (Proposition, informal) Bounds on the ATE

$$\psi_* \in [\mathcal{L}(\Gamma), \mathcal{U}(\Gamma)]$$

$$\mathcal{U}(\Gamma) = \mathbb{E} \left[ (1 - A) \underbrace{\theta_1^+ \{X; \exp(\Gamma M)\}}_{\text{depends on } M!} - A \theta_0^- \{X; \exp(\Gamma M)\} \right]$$

$$\mathcal{L}(\Gamma) = \mathbb{E} \left[ (1 - A) \theta_1^- \{X; \exp(\Gamma M)\} - A \theta_0^+ \{X; \exp(\Gamma M)\} \right]$$

where, e.g.,  $\theta_1^+(X; t)$  is the upper bound on  $\mathbb{E}(Y^1 \mid A = 0, X)$  with parameter  $t$  [Yadlowsky et al., 2022]

# Estimation and inference

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# Establishing convergence guarantees

1. **Establish that the bounds  $\mathcal{U}(\Gamma)$  and  $\mathcal{L}(\Gamma)$  are differentiable with respect to  $M$**

- can use Taylor's theorem (/delta method) when providing error guarantees
- involved proof when nuisance functions **depend on  $M$** , like  $\theta\{X; \exp(\Gamma M)\}$

2. **Establish estimator for  $M$  is regular and asymptotically linear (RAL) under doubly-robust-style conditions**

- Use efficient influence functions
- ⇒ bias is product of nuisance function errors (e.g.,  $\|\hat{\pi} - \pi\| \|\hat{\mu} - \mu\|$ )

3. **Establish estimator for bound  $\mathcal{U}(\Gamma)$  is RAL under doubly-robust-style conditions**

- Use steps #1 and #2 and efficient influence functions

## (Theorem, informal) Convergence guarantees for estimators for bounds, and inference for the ATE

Under doubly-robust-style conditions on the nuisance function estimators, (e.g.,  $\|\hat{\pi} - \pi\| \|\hat{\mu} - \mu\| = o_{\mathbb{P}}(n^{-1/2})$ ),

$$\hat{\mathcal{U}}(\Gamma) - \mathcal{U}(\Gamma) = (\mathbb{P}_n - \mathbb{P})\varphi_{\mathcal{U}}(Z) + o_{\mathbb{P}}(n^{-1/2})$$

$$\hat{\mathcal{L}}(\Gamma) - \mathcal{L}(\Gamma) = (\mathbb{P}_n - \mathbb{P})\varphi_{\mathcal{L}}(Z) + o_{\mathbb{P}}(n^{-1/2})$$

→  $\varphi_{\mathcal{U}}$  and  $\varphi_{\mathcal{L}}$  account for uncertainty in estimating  $M$

### Constructing confidence intervals for ATE:

→ Intersection one-sided Wald-type intervals for  $\mathcal{U}$  and  $\mathcal{L}$ .

# Summary

- To solve issues with standard sensitivity analyses and post hoc calibration, we proposed novel **calibrated sensitivity models**:  $U \leq \Gamma M$ ,
- Discussed model choices within a calibrated framework, in particular for measured confounding,
- Partially identified the ATE,
- Developed methods for estimation and inference which account for uncertainty in  $\hat{M}$

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Thank you for your attention!



## References

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